

# MATH-GA1002 Multivariable Analysis

Differential of a Function

Smooth Functions

Directional Derivatives of a Function

Derivations

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## Differential of a Function With Respect to Coordinates

- ▶ Recall that given a  $C^1$  function  $f : O \rightarrow \mathbb{R}$ , its differential at  $x \in O$  is the linear function

$$\begin{aligned}df(x) : \mathbb{R}^n &\rightarrow \mathbb{R} \\ v &\mapsto D_v f(x)\end{aligned}$$

- ▶ In particular, for each  $1 \leq k \leq n$ ,

$$\begin{aligned}\langle df(x), e_k \rangle &= D_{e_k} f(x) \\ &= \partial_k f(x)\end{aligned}$$

- ▶ Since  $(dx^1, \dots, dx^n)$  is the dual basis to  $(e_1, \dots, e_n)$ , it follows that

$$df(x) = \partial_k f(x) dx^k$$

- ▶ Therefore, for any  $v = e_k v^k \in \mathbb{R}^n$ ,

$$\begin{aligned}\langle df(x), v \rangle &= \langle \partial_j f(x) dx^j, e_k v^k \rangle \\ &= \partial_j f(x) v^k \langle dx^j, e_k \rangle \\ &= \partial_k f(x) v^k\end{aligned}$$

# Smooth Functions

- ▶ Let  $O \subset \mathbb{R}^n$  be open and consider a function  $f : O \rightarrow \mathbb{R}$
- ▶  $f$  is  $C^0$  on  $O$  if it is continuous
- ▶  $f$  is  $C^1$  on  $O$  if it is continuous and its partial derivatives are continuous
- ▶ Lemma: *If  $f$  is  $C^1$ , then it is differentiable*
- ▶  $f$  is  $C^k$  if  $f$  and its partial derivatives up to order  $k$  are continuous
- ▶  $f$  is  $C^\infty$  or **smooth** if  $f$  and its partial derivatives of all orders are continuous
- ▶ The space of all  $C^k$  functions with domain  $O$  is denoted  $C^k(O)$

# Properties of Directional Derivatives

- ▶ Given  $x_0 \in O$  and  $v \in \mathbb{R}^n$ , the directional derivative  $D_v$  is an operator

$$D_v : C^1(O) \rightarrow \mathbb{R}$$

$$f \mapsto \left. \frac{d}{dt} \right|_{t=0} f(x + tv)$$

- ▶ For any  $f_1, f_2 \in C^1(O)$  and  $a^1, a^2 \in \mathbb{R}$ ,
  - ▶ Constant factor and sum rules:

$$(D_v(a^1 f_1 + a^2 f_2))(x) = a^1 (D_v f_1)(x) + a^2 (D_v f_2)(x)$$

- ▶ Product rule:

$$(D_v(f_1 f_2))(x) = f_2(x) (D_v f_1)(x) + f_1(x) (D_v f_2)(x)$$

# Derivations

- ▶ Given an open  $O \subset \mathbb{R}^n$ , a map

$$D : C^\infty(O) \rightarrow \mathbb{R}$$

is a **derivation** at  $x \in O$  if the following holds:

- ▶ For any  $f_1, f_2 \in C^\infty(O)$  and  $a^1, a^2 \in \mathbb{R}$ ,
  - ▶ Constant factor and sum rules:

$$D(a^1 f_1 + a^2 f_2) = a^1 Df_1 + a^2 Df_2$$

- ▶ Product rule:

$$D(f_1 f_2) = f_2(x) Df_1 + f_1(x) Df_2$$

- ▶ A directional derivative is a derivation

## Derivation of Constant Function is Zero

- ▶ Let  $D$  be a derivation at  $x_0 \in O$
- ▶ For any  $c \in \mathbb{R}$  and  $f \in C^\infty(O)$ ,

$$\begin{aligned}D(cf) &= f(x_0)D(c) + cD(f), \text{ by product rule} \\ &= f(x_0)D(c) + D(cf), \text{ by constant factor rule}\end{aligned}$$

- ▶ Therefore  $D(c) = 0$

## A Derivation is a Directional Derivative (Part 1)

- By the Fundamental Theorem of Calculus,

$$\begin{aligned}f(x) &= f(x_0) + \int_{t=0}^{t=1} \frac{d}{dt} f(x_0 + t(x - x_0)) dt \\&= f(x_0) + \int_{t=0}^{t=1} (x^i - x_0^i) \partial_i f(x_0 + t(x - x_0)) dt \\&= f(x_0) + (x^i - x_0^i) \int_{t=0}^{t=1} \partial_i f(x_0 + t(x - x_0)) dt \\&= f(x_0) + \phi^i(x) b_i(x),\end{aligned}$$

where

$$\begin{aligned}\phi^i(x) &= x^i - x_0^i \\b_i(x) &= \int_{t=0}^{t=1} \partial_i f(x_0 + t(x - x_0)) dt\end{aligned}$$

## A Derivation is a Directional Derivative (Part 2)

- ▶ Therefore, if  $v^i = D(\phi^i)$ , then

$$\begin{aligned}D(f) &= D(f(x_0) + \phi^i b_i) \\&= b_i(x_0)D(\phi^i) + \phi^i(x_0)D(b_i) \\&= v^i \partial_i f(x_0) \\&= D_v f(x_0)\end{aligned}$$



# Fundamental Examples of Smooth Functions

- ▶ Constant function: For any  $c \in \mathbb{R}$ , the function

$$f(x) = c, \quad \forall x \in \mathbb{R}^n$$

- ▶  $df = 0$

- ▶ Coordinate functions: For each  $i \in \{1, \dots, n\}$ , the function

$$\begin{aligned} x^i &: \mathbb{R}^n \rightarrow \mathbb{R} \\ (a^1, \dots, a^n) &\mapsto a^i \end{aligned}$$

- ▶  $dx^i = \epsilon^i$

# Partial Derivatives Commute

- ▶ If  $f : O \rightarrow \mathbb{R}$  is  $C^2$ , then

$$(\partial_i(\partial_j f))(x) = (\partial_j(\partial_i f))(x)$$

- ▶ We shall denote

$$\partial_{ij}^2 f = \partial_i(\partial_j f) = \partial_j(\partial_i f)$$