

Chapter 9

Girsanov Formula

If α is Gaussian with mean b_1 and variance a while β has the same variance but a mean b_2 the Radon-Nikodym derivative can be explicitly calculated

$$\frac{d\beta}{d\alpha}(x) = e^{-\frac{(x-b_2)^2}{2a} + \frac{(x-b_1)^2}{2a}} = e^{\frac{(b_2-b_1)(x-b_1)}{a} - \frac{(b_2-b_1)^2}{2a}}$$

This suggests that if $P \in \mathcal{I}(a, b)$ and $Q \in \mathcal{I}(a, b + ac)$ for some bounded c , then

$$\frac{dQ}{dP}|_{\mathcal{F}_t} = \exp\left[\int_{s_0}^t c(s, x(s))dy(s) - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))c(s, x(s)), c(s, x(s)) \rangle ds\right]$$

where

$$y(t) = x(t) - \int_{s_0}^t b(s, x(s))ds$$

Theorem 9.1. *With*

$$R(t, \omega) = \exp\left[\int_{s_0}^t c(s, x(s))dy(s) - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))c(s, x(s)), c(s, x(s)) \rangle ds\right]$$

if $P \in \mathcal{I}(a, b)$ then Q with $\frac{dQ}{dP}|_{\mathcal{F}_t} = R(t, \omega)$ is in $\mathcal{I}(a, b + ac)$ and conversely if $Q \in \mathcal{I}(a, b + ac)$ then P with $\frac{dP}{dQ}|_{\mathcal{F}_t} = \frac{1}{R(t, \omega)}$ is in $\mathcal{I}(a, b)$.

Proof. If $P \in \mathcal{I}(a, b)$ then with

$$y(t) = x(t) - \int_{s_0}^t b(s, x(s))ds$$

$$R(t, \omega) = \exp\left[\int_{s_0}^t c(s, x(s)) \cdot dy(s) - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))c(s, x(s)), c(s, x(s)) \rangle ds\right]$$

is martingale. We can define Q by $\frac{dQ}{dP}|_{\mathcal{F}_t} = R(t, \omega)$. We can replace c by $c(s, x) + \theta$ and will have

$$\begin{aligned} R(t, \theta, \omega) &= \exp \left[\int_{s_0}^t (\theta + c(s, x(s))) \cdot dy(s) \right. \\ &\quad \left. - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))(\theta + c(s, x(s))), (\theta + c(s, x(s))) \rangle ds \right] \\ &= R(t, \omega) \exp \left[\langle \theta, y(t) - y(s_0) \rangle - \int_{s_0}^t \langle a(s, x(s))c(s, x(s)), \theta \rangle \right. \\ &\quad \left. - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))\theta, \theta \rangle \right] \end{aligned}$$

is a martingale for all θ . It is easy to see that this equivalent to

$$\begin{aligned} &\exp \left[\langle \theta, y(t) - y(s_0) \rangle - \int_{s_0}^t \langle \theta, a(s, x(s))c(s, x(s)) \rangle ds \right. \\ &\quad \left. - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))\theta, \theta \rangle ds \right] \\ &= \exp \left[\langle \theta, x(t) - x(s_0) \rangle - \int_{s_0}^t \langle \theta, b(s, x(s)) + a(s, x(s))c(s, x(s)) \rangle ds \right. \\ &\quad \left. - \frac{1}{2} \int_{s_0}^t \langle a(s, x(s))\theta, \theta \rangle ds \right] \end{aligned}$$

being a martingale with respect to $(C[s_0, T], \mathcal{F}_t, Q)$ i.e. $Q \in \mathcal{I}(a, b + ac)$. The steps can be retraced to prove the converse. \square