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Modeling the interaction of a structure with the ground.

Let the surface of the ground be

$$H(\underline{x}) = 0,$$

with $H(\underline{x}) > 0$ above the ground
and $H(\underline{x}) < 0$ below the ground.

Let $\underline{x}(t)$ be any point of a structure
that interacts with the ground, and
let $\underline{v}(t)$ be the velocity of that point.

We allow the point $\underline{x}(t)$ to go below
the surface, but when it does so,
it experiences a force pushing it out
and also a tangential force that
models sliding friction.

The normal direction to the ground,
pointing upwards, is approximately
given by

$$\frac{\nabla H}{\|\nabla H\|}$$

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and the distance below the ground when $H(\underline{x}) < 0$ is approximately given by

$$\frac{-H(\underline{x})}{\|\nabla H(\underline{x})\|}$$

see APPENDIX for justification of these statements.

Also, the tangential velocity is approximately given by

$$\underline{U}^{(tan)} = \underline{U} - \frac{\underline{U} \cdot \nabla H(\underline{x})}{\|\nabla H(\underline{x})\|} \frac{\nabla H(\underline{x})}{\|\nabla H(\underline{x})\|}$$

Any point of the structure for which $H(\underline{x}) < 0$ therefore feels a force given by

$$\underline{F} = S \frac{-H(\underline{x})}{\|\nabla H(\underline{x})\|} \frac{\nabla H(\underline{x})}{\|\nabla H(\underline{x})\|}$$

$$- \mu S \frac{-H(\underline{x})}{\|\nabla H(\underline{x})\|} \frac{\underline{v}^{(tan)}}{\|\underline{v}^{tan}\|}$$

$$= S \frac{-H(\underline{x})}{\|\nabla H(\underline{x})\|} \left(\frac{\nabla H(\underline{x})}{\|\nabla H(\underline{x})\|} - \mu \frac{\underline{v}^{(tan)}}{\|\underline{v}^{tan}\|} \right)$$

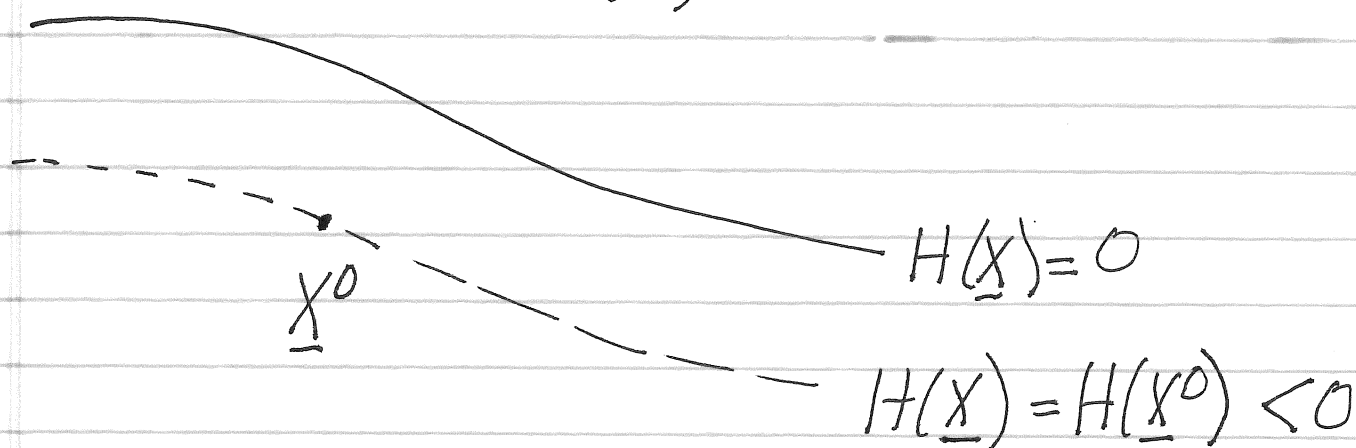
Here μ is the coefficient of sliding friction.

Recall that sliding friction is proportional to the normal force and in the direction opposing the tangential motion.

APPENDIX

$$H(\underline{x}) > 0$$

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$$H(\underline{x}) = H(\underline{x}^0) + (\nabla H)^0 \cdot (\underline{x} - \underline{x}^0) + \dots$$

The surface $H(\underline{x}) = H(\underline{x}^0)$ is therefore given by

$$0 = (\nabla H)^0 \cdot (\underline{x} - \underline{x}^0) + \dots$$

If we drop \dots , we get the equation of the tangent plane to this surface, namely

$$0 = (\nabla H)^0 \cdot (\underline{x} - \underline{x}^0)$$

This shows that $(\nabla H)^0$ is normal to the tangent plane to the surface $H(\underline{x}) = H(\underline{x}^0)$ at the point $\underline{x} = \underline{x}^0$, since it is orthogonal to $\underline{x} - \underline{x}^0$ for every \underline{x} in the tangent plane. By definition, being normal to the tangent plane is the same thing as being normal to the surface.

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Now we seek an approximate formula for the distance between a point \underline{x}^0 and the closest point on the surface $H(\underline{x}) = 0$.

Instead of using the exact function $H(\underline{x})$ we use its linear approximation in the neighborhood of \underline{x}^0 . Thus, we seek \underline{x} that minimizes

$$\|\underline{x} - \underline{x}^0\|^2$$

subject to the constraint

$$0 = H(\underline{x}^0) + (\nabla H)^0 \cdot (\underline{x} - \underline{x}^0)$$

let

$$\underline{N}^0 = \frac{(\nabla H)^0}{\|(\nabla H)^0\|}$$

Then

$$0 = \frac{H(\underline{x}^0)}{\|(\nabla H)^0\|} + \underline{N}^0 \cdot (\underline{x} - \underline{x}^0)$$

We can always write

$$\underline{(x - x^0)} = \left(\underline{(x - x^0)} \cdot \underline{N^0} \right) \underline{N^0} + \underline{z}$$

and then $\underline{z} \cdot \underline{N^0} = 0$, so

$$\begin{aligned} \|\underline{x - x^0}\|^2 &= \left(\underline{(x - x^0)} \cdot \underline{N^0} \right)^2 + \|\underline{z}\|^2 \\ &= \left(\frac{H(x^0)}{\|\underline{(\nabla H)^0}\|} \right)^2 + \|\underline{z}\|^2 \end{aligned}$$

Clearly the choice of \underline{z} that minimizes this expression is $\underline{z} = 0$, and then we have

$$\|\underline{x - x^0}\| = \frac{|H(x^0)|}{\|\underline{(\nabla H)^0}\|}$$

(Here \underline{x} is the point that solves the minimization problem.)

If $H(x^0) < 0$, which is the case of interest

$$\|\underline{x - x^0}\| = \frac{-H(x^0)}{\|\underline{(\nabla H)^0}\|}$$