

$$\kappa(A) = \|A\| \cdot \|A^{-1}\|$$

Condition # of matrix

$$A = \begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & & \ddots & & \\ & & & 1 & -2 & 1 \\ & & & & 1 & -2 \end{bmatrix}$$

$\in \mathbb{R}^{n \times n}$

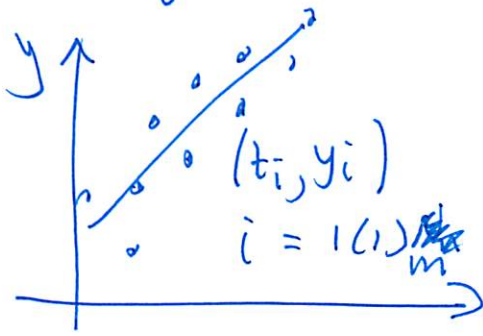
A commonly inverted tridiagonal matrix.

i.e. $u_{xx} = f$ on $[0,1]$
 $u(0) = a, u(1) = b$

$$Ax = b$$

n	$\kappa_2(A) \approx n^2$
10	60
20	220
100	5100
1000	5.1×10^5

Least Squares problems



Problem: Given ~~measure~~ measurements, ~~fit~~ find "best-fit" line $y = c + d$ to the data.

There is no single line going through all the data for $m > 2$. This problem is "over-determined", i.e. more constraints (m pairs (t_i, y_i)) than unknowns $[2 - (c, d)]$.

$$\begin{aligned}
 y_1 &= at_1 + b \\
 &\vdots \\
 y_m &= at_m + b
 \end{aligned}
 \Leftrightarrow
 \begin{bmatrix}
 t_1 & 1 \\
 \vdots & \vdots \\
 t_m & 1
 \end{bmatrix}
 \begin{bmatrix}
 c \\
 d
 \end{bmatrix}
 =
 \begin{bmatrix}
 y_1 \\
 \vdots \\
 y_m
 \end{bmatrix}$$

$A \quad \times \quad b$

There is generally no solution to this problem. Instead, ~~pose~~ look for a "best-fit" pair (c, d) that satisfies a "least-squares" problem.

Given $A \in \mathbb{R}^{m \times n}$, $m > n$

~~$x \in \mathbb{R}^n$~~
 $b \in \mathbb{R}^m$

Find $x \in \mathbb{R}^n$ satisfying

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2$$

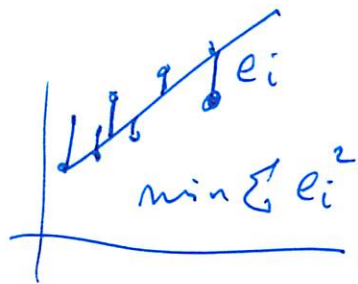
or equivalently ~~task~~

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2 \leftarrow \text{least squares.}$$

For the line fit problem:

$$\min_{(c, d)} \sum_{k=1}^n (ct_i + d - y_i)^2$$

$n=2$



~~$f: \mathbb{R}^n \rightarrow \mathbb{R}^+$~~ Recall $\|y\|_2^2 = y^T y = y \cdot y$

~~$f(x)$~~ $\Rightarrow f(x) = \|Ax - b\|_2^2: \mathbb{R}^m \rightarrow \mathbb{R}^+$

$$= (Ax - b)^T (Ax - b)$$

$$= x^T A^T A x - (x^T A^T b + b^T A x)$$

$$= x^T (A^T A) x - 2 x^T A^T b + b^T b$$

Find $x_* \in \mathbb{R}^n$ s.t. $\nabla f(x_*) = 0$ (i.e. a critical pt)

$$f(x) = \sum_{i=1}^n (x_i (A^T)_{ij} - 2 \sum_{i=1}^n x_i (A^T)_{ij})$$

$1 \leq i, j \leq n$ $1 \leq i \leq n$
 $1 \leq j \leq m$

$$f = (Ax)^T (Ax) - z (Ax)^T b + b^T b$$

$$g_i = \sum_j a_{ij} x_j$$

$$\frac{\partial g_i}{\partial x_p} = \cancel{a_{ip}} a_{ip}$$

$$f = \sum_i g_i(x)^2 - z \sum_i g_i(x) b_i + b^T b$$

$$(\nabla f)_p = \frac{\partial f}{\partial x_p} = 2 \sum_i g_i(x) a_{ip} - z \sum_i a_{ip} b_i$$

$$= 2 \sum_i a_{ip} (g_i(x) - b_i)$$

$$= 2 \sum_i (A^T)_{pi} \left(\sum_j (A)_{ij} x_j - b_i \right)$$

$$\text{or } \nabla f(x) = 2 (A^T A x - A^T b) \quad \checkmark$$

The normal equations: Critical point x_*

satisfies

$$\boxed{A^T A x = A^T b}$$

$$A^T A \in \mathbb{R}^{n \times n}, \quad A^T b \in \mathbb{R}^n$$

Solving these equations solves the least squares problem, but the normal equations can be poorly conditioned.

Example $A = \begin{pmatrix} \varepsilon & 0 \\ 0 & 1 \end{pmatrix}; A^{-1} = \begin{pmatrix} \varepsilon^{-1} & 0 \\ 0 & 1 \end{pmatrix} \quad 0 < \varepsilon \ll 1$

$\# \quad B \approx A^T A = \begin{pmatrix} \varepsilon^2 & 0 \\ 0 & 1 \end{pmatrix}$

$$\kappa_2(A) = \|A\|_2 \cdot \|A^{-1}\|_2 = 1 \cdot \varepsilon^{-1} = 1/\varepsilon$$

$$\kappa_2(A^T A) = 1/\varepsilon^2$$

Essentially, you squared the condition # of A .

There are better ways:

Orthogonal matrix $Q \in \mathbb{R}^{m \times m}$ satisfies

$$Q^T Q = I \in \mathbb{R}^{m \times m} \quad \left(\begin{array}{l} \text{i.e. } Q^T = Q^{-1} \\ \Rightarrow Q Q^T = I \end{array} \right)$$

i.e. all columns of Q are ~~mutually~~ unit vectors and mutually orthogonal.

Note $\|Qx\|_2 = \left((Qx)^T (Qx) \right)^{1/2}$
 $= \left(x^T \underbrace{Q^T Q}_{=I} x \right)^{1/2} = \|x\|_2$

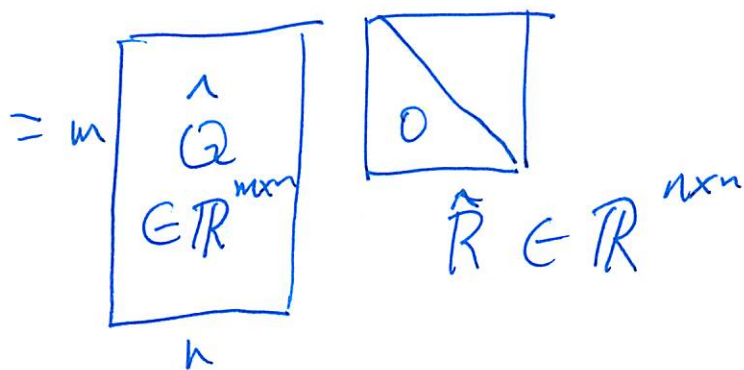
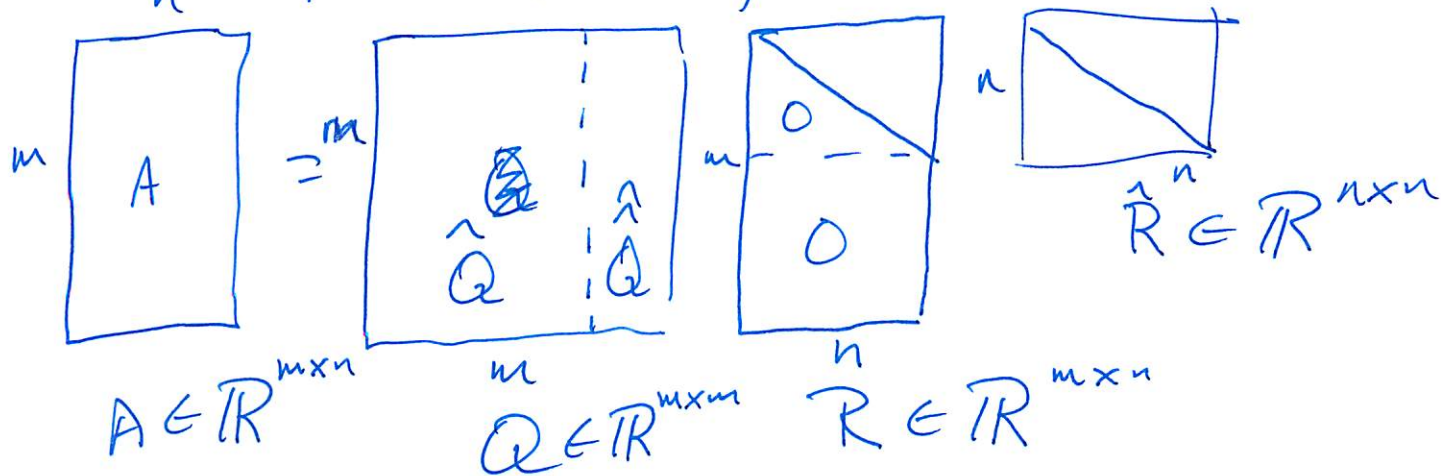
$$\Rightarrow \|Q\|_2 = 1.$$

Thm Given $A \in \mathbb{R}^{m \times n}$, $m \geq n$.

Then \exists ~~Q~~ orthogonal $Q \in \mathbb{R}^{m \times m}$

and upper triangular $R \in \mathbb{R}^{m \times n}$ s.t.

$A = QR$; called the QR-decomp



The columns of \hat{Q} remain unit vectors that are mutually orthogonal. Hence

$$\hat{Q}^T \hat{Q} = I \in \mathbb{R}^{n \times n} \quad (\text{recall } n < m)$$

$n \times m$
 $m \times n$

Thm The solution x_* for the least-squares problem

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2 \text{ satisfies}$$

$$\hat{R}x = \hat{Q}^T b \leftarrow \begin{array}{l} \text{requires matrix} \\ \text{decomp (still } \sim m^3) \\ \text{+ back solve.} \end{array}$$

Pf. $\|Ax - b\|_2^2 = (Ax - b)^T (Ax - b)$

$$= (Ax - b)^T Q Q^T (Ax - b) = \|Q^T (Ax - b)\|_2^2$$

$\downarrow A = QR, Q^T Q = I$

$$= \|Rx - Q^T b\|_2^2 = \left\| \begin{pmatrix} \hat{R}x \\ 0 \end{pmatrix} - \begin{pmatrix} \hat{Q}^T b \\ c \end{pmatrix} \right\|_2^2$$

$$= \underbrace{\|\hat{R}x - \hat{Q}^T b\|_2^2}_{\text{1st term minimized}} + \underbrace{\|c\|_2^2}_{\text{indep. of } x}$$

1st term minimized

by setting $\boxed{\hat{R}x = \hat{Q}^T b}$

This is well-conditioned to ~~A~~ setting

~~The condition #~~ (who sets the condition # ? $(\kappa(A^T A))^{1/2}$?)