

**PDE I – Problem Set 1.** Distributed Wed 9/3/2014, due Tues 9/16/2014.

- (1) Recall from Lecture 1 that for a 1D random walk with spatial step  $\Delta x$ , time step  $\Delta t$ , and probability  $1/2$  of going left or right, the evolution of the probability density is a finite-difference discretization of  $u_t = u_{xx}$  when  $\frac{(\Delta x)^2}{2\Delta t} = 1$ .
- (a) Consider the biased random walk in which a walker at  $j\Delta x$  moves to  $(j+1)\Delta x$  with probability  $\frac{1}{2} + \alpha\Delta x$  and moves to  $(j-1)\Delta x$  with probability  $\frac{1}{2} - \alpha\Delta x$ ? Assuming as before that  $\frac{(\Delta x)^2}{2\Delta t} = 1$ , and taking  $\alpha$  to be constant, what PDE does the probability density solve in the continuum limit  $\Delta x \rightarrow 0$ ?
- (b) Now suppose the bias is position-dependent; in other words, using the notation of part (a), suppose  $\alpha = \alpha(j\Delta x)$  is a smooth but non-constant function of position. Extend what you found in part (a) to this case. [Warning: note that when  $\alpha(x)$  is not constant,  $\alpha u_x \neq (\alpha u)_x$ .]
- (2) In the Lecture 1 notes, the discussion of convection and diffusion (“motivation 1”) is quite different from the discussion of probability (“motivation 2”), and there is no discussion about how population dynamics leads to a reaction-diffusion equation. This two-part question provides some amplification.
- (a) Use an argument similar to that of “motivation 1” to show that if the population density is  $u(x, t)$ , the birth rate is  $f_1(u)$ , the death rate is  $f_2(u)$ , and diffusion is governed by Fick’s law, then  $u_t = D\Delta u + f(u)$  with  $f = f_1 - f_2$ .
- (b) Reconcile the apparently different treatments of “motivation 1” and “motivation 2” by showing that if  $u_j^n = u(j\Delta x, n\Delta t)$  satisfies

$$\frac{u_j^{n+1} - u_j^n}{\Delta t} = \frac{(\Delta x)^2}{2\Delta t} \frac{u_{j+1}^n + u_{j-1}^n - 2u_j^n}{(\Delta x)^2}$$

then for any  $j < k$  and any  $n$ ,

$$\left[ u(j\Delta x, t) + u((j+1)\Delta x, t) + \cdots + u(k\Delta x, t) \right]_{t=n\Delta t}^{t=(n+1)\Delta t} = \frac{u_{k+1}^n - u_k^n}{2} - \frac{u_j^n - u_{j-1}^n}{2}.$$

Why is this analogous to the conservation law considered in “motivation 1”?

- (3) The Lecture 1 notes use an “energy-type” argument to show that if  $\Omega$  is a bounded domain in  $R^n$ , then the evolution problem

$$u_t - \Delta u = f \text{ in } \Omega \text{ for } t > 0, \text{ with } u = \phi \text{ at } \partial\Omega \text{ and } u = u_0 \text{ at } t = 0$$

has at most one solution. They also show that if  $f$  and  $\phi$  are independent of time, and accepting the existence of a steady-state solution  $\bar{u}$  (solving  $-\Delta\bar{u} = f$  in  $\Omega$ , with  $\bar{u} = \phi$  at  $\partial\Omega$ ), we have

$$\frac{d}{dt} \int_{\Omega} |u - \bar{u}|^2 dx \leq -C \int_{\Omega} |u - \bar{u}|^2 dx \tag{1}$$

with  $C > 0$ , so that  $u - \bar{u} \rightarrow 0$  exponentially fast (in  $L^2$ ) as  $t \rightarrow \infty$ . Let’s examine what happens when the boundary condition is of Neumann rather than Dirichlet type.

- (a) Use an “energy-type” argument to show that if  $\Omega$  is a bounded domain in  $R^n$ , then the evolution problem

$$u_t - \Delta u = f \text{ in } \Omega \text{ for } t > 0, \text{ with } \frac{\partial u}{\partial n} = \psi \text{ at } \partial\Omega \text{ and } u = u_0 \text{ at } t = 0 \quad (2)$$

has at most one solution. In the special case  $f = 1$ ,  $u_0 = 0$ ,  $\psi = 0$ , can you write down the solution explicitly?

- (b) Now suppose  $f$  and  $\psi$  are independent of time. Observe that for the steady-state problem ( $-\Delta \bar{u} = f$  in  $\Omega$  with  $\frac{\partial \bar{u}}{\partial n} = \psi$  at  $\partial\Omega$ ) to have a solution,  $f$  and  $\psi$  must satisfy the *consistency condition*  $\int_{\partial\Omega} \psi \, ds + \int_{\Omega} f \, dx = 0$ . Also that if the steady-state problem has a solution at all, then it is non-unique since for any constant  $c$ ,  $\bar{u} + c$  is another solution. Assuming the existence of a steady-state solution (something we’ll prove later on; we are assuming here of course that  $f$  and  $\psi$  are consistent), show that when  $u$  solves (2) it satisfies an estimate of the form (1), with  $\bar{u}$  chosen so that  $\int_{\Omega} \bar{u} \, dx = \int_{\Omega} u_0 \, dx$ . [Note: you’ll need to use the mean-value-zero analogue of Poincaré’s inequality. It asserts the existence of a constant  $M_{\Omega}$  such that  $\int_{\Omega} g^2 \, dx \leq M_{\Omega} \int_{\Omega} |\nabla g|^2 \, dx$  for any function  $g$  such that  $\int_{\Omega} g \, dx = 0$ . You may use this result without proving it. Incidentally: the best choice of  $M_{\Omega}$  is  $1/\lambda$ , where  $\lambda$  is the first nonzero eigenvalue of the Laplacian with a Neumann boundary condition at  $\partial\Omega$ .]
- (c) Finally, suppose  $f$  and  $\psi$  are independent of time but inconsistent in the sense that  $\int_{\partial\Omega} \psi \, ds + \int_{\Omega} f \, dx \neq 0$ . What is the large-time behavior of the solution of (2)?
- (4) In the Lecture 1 notes, “motivation 4” was the modeling of heat transfer. In that setting, a physically natural assumption is that the heat flux at the boundary is proportional to the difference between the temperature  $u(x, t)$  and some fixed constant  $U$ . Known as “Newton’s law of cooling”, this models loss of heat by radiation, if the far-field temperature is  $U$ . So let’s consider the heat equation  $u_t = \Delta u$  in a bounded domain  $\Omega \subset R^n$ , with initial condition  $u = u_0(x)$  at  $t = 0$  and boundary condition

$$\frac{\partial u}{\partial n} = -k(u - U) \text{ at } \partial\Omega.$$

where  $k$  and  $U$  are constants.

- (a) Assuming that  $k > 0$ , use an “energy-type argument” to show that this evolution problem has at most one solution.
- (b) When  $k < 0$  the same conclusion is valid, but you’ll have to work harder to prove it. Give a proof based on the assertion that for any  $\varepsilon > 0$  there exists  $C_{\varepsilon} > 0$  such that

$$\int_{\partial\Omega} v^2 \, ds \leq C_{\varepsilon} \int_{\Omega} v^2 \, dx + \varepsilon \int_{\Omega} |\nabla v|^2 \, dx. \quad (3)$$

- (c) Prove the estimate (3) for a domain with a sufficiently smooth boundary. [Hint: one argument begins by choosing a smooth vector field  $\sigma$  on  $\Omega$  such that  $\sigma =$  outward unit normal at  $\partial\Omega$ . Then  $\int_{\partial\Omega} v^2 \, ds = \int_{\partial\Omega} v^2 \sigma \cdot n \, ds = \int_{\Omega} \operatorname{div}(\sigma v^2) \, dx = \dots]$
- (5) Consider the semilinear equation

$$u_t - \Delta u = u^5,$$

in a bounded domain  $\Omega \subset R^n$ , with Dirichlet boundary condition  $u = 0$  at  $\partial\Omega$  and initial condition  $u(x, 0) = u_0(x)$ . Show that if

$$E[u_0] = \int_{\Omega} \left( \frac{1}{2} |\nabla u_0|^2 - \frac{1}{6} u_0^6 \right) dx < 0$$

then the solution “blows up,” i.e. a classical solution ceases to exist in finite time. [Hint: start by noting that  $\frac{d}{dt}E[u(t)] \leq 0$ . Then derive a relation linking  $\frac{d}{dt} \int_{\Omega} u^2 dx$  with  $E[u(t)]$ .]