

PDE - Lecture 7, 10/28/2014

Continuing with Laplace-type eqns.

Major topics in Lecture 5 + 6 notes were

- examples + motivations
- uniqueness (improved on Prob Set 6 to proofs of well-posedness) in bounded domains
- mean value property, with applies ($\Delta u = 0$ in \mathbb{R}^n + sublinear growth at $\infty \Rightarrow u = \text{const}$; $\Delta u = 0 \Rightarrow u$ is C^∞)
- soln formula to $\Delta u = f$ in \mathbb{R}^n (with sublinear growth at ∞): The Fundamental soln
- weak + strong forms of max prin
- Poisson's kernel, for a ball in \mathbb{R}^2 .

This is a lot, but it falls short by giving us

a) no representation for solns of $\Delta u = f$ in bdd $\Omega \subset \mathbb{R}^n$ (with bc such as $u = g$ at $\partial\Omega$), except in special cases such as a ball $\subset \mathbb{R}^2$

b) no suggestion how solns could be found numerically (except by finite differences)

These notes focus on topic (a), by discussing the Green's function of a bounded domain Ω .
By defn, it is a fn

$$G(x, y) \text{ defined for all } x, y \in \Omega \\ \text{at } x \neq y$$

with the property that

$$-\Delta_y G(x, y) = \delta_x$$

$$G(x, y) = 0 \text{ for } y \in \partial\Omega$$

(we think of x being a parameter, + $G(x, y) = u(y)$ the soln of the pde $-\Delta u = \delta_x$ in Ω , $u = 0$ at $\partial\Omega$). We'll show shortly that $G(x, y) = G(y, x)$, so while the defn is asymmetric G is actually symmetric.

Utility of this: given G , soln of

$$(*) \quad \begin{aligned} -\Delta u &= f \text{ in } \Omega \\ u &= \varphi \text{ at } \partial\Omega \end{aligned}$$

$$\text{is } u(x) = \int_{\Omega} G(x, y) f(y) dy - \int_{\partial\Omega} \varphi(y) \nabla_y G(x, y) \cdot \vec{n}$$

Pf: In general

$$\int_{\Omega} v \Delta u - u \Delta v = \int_{\partial\Omega} v \frac{\partial u}{\partial n} - u \frac{\partial v}{\partial n}$$

Fixing x , take $v(y) = G(x, y)$ + let u solve $(*)$;
Then

$$\int_{\Omega} u \Delta v = - \int_{\Omega} u \delta_x = -u(x)$$

$$\int_{\Omega} v \Delta u = - \int_{\Omega} G(x, y) f(y) dy$$

$$\int_{\partial\Omega} u \frac{\partial v}{\partial n} = \int_{\partial\Omega} \Phi \nabla_y G(x, y) \cdot \vec{n}$$

$$\int_{\partial\Omega} v \frac{\partial u}{\partial n} = 0 \quad \text{since } v = 0 \text{ at } \partial\Omega$$

Does such a G exist? Yes, for any "reasonable" domain, we can "construct" it by taking

$$G(x, y) = \Phi(x-y) + v^{(x)}(y)$$

fund soln

soln of $\Delta_y v^{(x)} = 0$ in Ω
with bdy data
 $v^{(x)} = -\Phi(x-y), y \in \partial\Omega$

(provided we accept that solns of $\Delta_y v = 0$ exist

4 are nice when the bdy data are nice).

For some special cases G can be made explicit, using tricks like those we used to find the Green's fn for the heat eqn (same name and analogies, but different defn of course!)

For a half-space: if $x = (x', x_n) \in \mathbb{R}^n$ and $\Omega = \{x_n > 0\}$ then

$$G(x, y) = \Phi(y-x) - \Phi(y-\tilde{x})$$

where $\tilde{x} =$ "reflection of x abt $\partial\Omega$ " $= (x', -x_n)$.
Defining properties of G are clear by inspection.

Note resemblance to what we did for heat eqn in a half-space. In special case when bc $g=0$, soln of $-\Delta u = f$ in $\{x_n > 0\}$ with $u=0$ is obtained by taking odd extension \tilde{f} of f , then solving $-\Delta \tilde{u} = \tilde{f}$ in \mathbb{R}^n , then restricting to $x_n > 0$. Since \tilde{u} is odd, it is the desired soln + it is equal to $\int_{x_n > 0} G(x, y) f(y)$ with G as given above.

For a ball: similar idea, but "reflection" is

replaced by inversion; for $\Omega = B_r(0)$,

$$G(x, y) = \bar{\Phi}(y-x) - \bar{\Phi}(|x|(y-\tilde{x}))$$

where $\tilde{x} = x/|x|^2$, (Crucial fact that makes this work: when $x \in B_r(0) \neq y \in \partial B_r(0)$, $|y-x| = |x||y-\tilde{x}|$.)

In 2D, focusing on $\Delta u = 0$ with $u = g$ at ∂B , we recover the 2D Poisson Kernel discussed in Lecture 6 notes. In higher dims we get

$\Delta u = 0$ in $B_r(0) \subset \mathbb{R}^n$, $u = g$ at bdy

$$\Rightarrow u(x) = \frac{r^2 - |x|^2}{n \alpha_n r} \int_{\partial B_r(0)} \frac{g(y)}{|x-y|^{n-2}} dA_y$$

which is Poisson's kernel for the ball in \mathbb{R}^n .

I promised a pf that $G(x, y) = G(y, x)$. Here is a "formal" pf: recall

$$\int_{\Omega} u \Delta v - v \Delta u = \int_{\partial \Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}$$

Take $u(y) = G(P, y) + v(y) = G(Q, y)$ with $P \neq Q$.

Then $-\Delta u = \delta_P$, $-\Delta v = \delta_Q$ and both vanish at $\partial\Omega$, So

$$-\int_{\Omega} u \delta_Q + \int_{\Omega} v \delta_P = 0$$

ie

$$G(P, Q) = G(Q, P).$$

(This pt is easily made honest, by the same argument we used to see that Φ was the fund soln.)

Similar technique can be used to solve Neumann bvp's. Just use $N(x, y)$ defined by

$$-\Delta_y N(x, y) = \delta_x \quad \text{for } y \in \Omega$$

$$\frac{\partial N}{\partial \nu_y} = \text{const} \quad \text{for } y \in \Omega$$

(The value of the constant in the bc is determined by $\int_{\partial\Omega} \frac{\partial N}{\partial \nu_y} = \int_{\Omega} \Delta_y N = -1$)

N is called the "Neumann function of Ω ".
Recall that

$$-\Delta u = f \text{ in } \Omega$$

$$\frac{\partial u}{\partial \nu} = g \text{ at } \partial \Omega$$

has a soln only if data are consistent:

$$\int_{\partial \Omega} g + \int_{\Omega} f = 0,$$

and that (for consistent data) soln is unique only up to an additive constant.

We can choose the constant st $\int_{\Omega} u = 0$.

Claim: For the soln normalized this way,

$$u(x) = \int_{\Omega} N(x,y) f(y) dy + \int_{\partial \Omega} N(x,y) g(y) dA_y$$

Pf.
$$\int_{\Omega} u \Delta N - N \Delta u = \int_{\partial \Omega} u \frac{\partial N}{\partial \nu} - N \frac{\partial u}{\partial \nu}$$

$$\Rightarrow -u(x) + \int_{\Omega} N(x,y) f(y) dy = 0 - \int_{\partial \Omega} N(x,y) g(y) dA$$

As for the Green's fn, N is symmetric in $x+y$ (same pf as for G) + we can easily write $N(x,y)$ as sum of $\tilde{G}(x-y)$ and a harmonic correction.