

## PDE - Lecture 4, 9/24/2013

We turn now to Laplace's eqn, + related problems. Some examples of how such pblms arise

(1) Heat transfer : we discussed how

$$\begin{aligned}u_t - \Delta u &= f & \text{in } \Omega, & t > 0 \\ u &= \varphi & \text{at } \partial\Omega.\end{aligned}$$

arises as a simple model for the evolution of the temperature  $u$  in a body; here  $f$  comes from sources or sinks of heat in  $\Omega$ , + the bc assumes temp is fixed at  $\partial\Omega$ . As  $t \rightarrow \infty$ , we expect decay to

$$\begin{aligned}-\Delta u &= f & \text{in } \Omega \\ u &= \varphi & \text{at } \partial\Omega.\end{aligned}$$

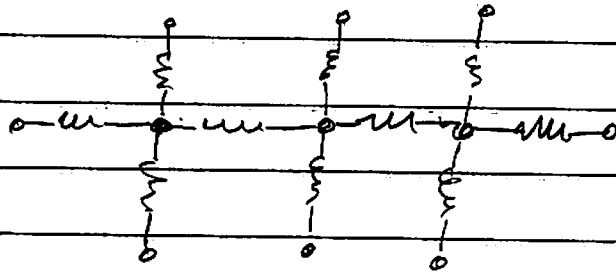
(if  $\varphi + f$  are indep of time).

Same story applies in all  $\mathbb{R}^n$ , eg with  $u(x, t) \rightarrow 0$  as  $|x| \rightarrow \infty$ . Then we expect decay as  $t \rightarrow \infty$  to soln of

$$-\Delta u = f \quad \text{in } \mathbb{R}^n.$$

(cont at  $\infty$  plays role of a bc)

(2) continuum limit of current flow in a resistor network: work in 2D for simplicity



spatial mesh  $h$ ;

$u_{ij}$  = voltage at  $i, j$ <sup>th</sup> node  
(spatial pt  $i, j$ )

current flow from  $i, j$  to  $i+1, j$  is  
proportional to  $u_{i+1, j} - u_{i, j}$  (Ohm's Law)

similar convention for vertical links.

total current balance in/out of node  $i, j$ :

$$u_{i+1, j} + u_{i-1, j} + u_{i, j+1} + u_{i, j-1} - 4u_{i, j} = 0$$

Finite difference approx of  $\nabla^2 u = 0$

Note: if there are current sources at nodes, then (assuming appropriate scaling)

we get by the same argt a finite difference approx of  $\Delta u = f$ .

### (3) probability - steady-state distn.

We saw in HW 1 that a biased random walk provides finite-difference analogue of

$$u_t = u_{xx} - (\alpha(x)u)_x = 0$$

As  $t \rightarrow \infty$ , we may expect convergence to

$$u_{xx} - (\alpha(x)u)_x = 0,$$

representing the steady-state probability distn.

Warning: if  $\alpha = 0$  and the initial data decay to 0 as  $x \rightarrow \infty$  then  $u \rightarrow 0$  as  $x \rightarrow 0$ . But in other cases there can be a nonzero limit. For example if bias always pushes walker toward 0, say

$$\alpha(x) = -x$$

then  $u = C e^{-\frac{1}{2}x^2}$  solves  $u_{xx} + (xu)_x = 0$

(4) probability - expected arrival at bdry

In 1D as usual, moving left or right with prob  $\frac{1}{2}$  (unbiased) + time step  $\Delta t$  so  $(\Delta x)^2 / 2\Delta t = 1$

$u(j\Delta x)$  = expected time when walker reaches bdry, starting from  $j\Delta x$  at  $T=0$

$$u(j\Delta x) = \frac{1}{2} u((j-1)\Delta x) + \frac{1}{2} u((j+1)\Delta x) + \Delta t$$

expected arrival time starting from next step

$$\Rightarrow u_{j-1} + u_{j+1} - 2u_j = -2\Delta t = -(\Delta x)^2$$

Discretization of  $u_{xx} = -1$ . Bdry cond is  $u=0$  at  $\partial\Omega$ .

In 2D, if walker goes to each of 4 nearest neighbors with equal prob, get similarly a discretization of

$$u_{xx} + u_{yy} = -1 \quad \text{if} \quad \frac{4\Delta t}{(\Delta x)^2} = 1$$

( $u=0$  at bdry)

(5) incompressible, irrotational flow (see eg Kevorkian, opening of Chap 2)

$\vec{q}$  = fluid velocity (a vector field)

$\operatorname{div} \vec{q} = 0 \iff$  incompressibility

$\operatorname{curl} \vec{q} = 0 \iff$  flow is "irrotational"

The latter implies  $\vec{q} = \nabla \phi$ . Then  $\operatorname{div} \vec{q} = 0 \iff \Delta \phi = 0$ .

(6) complex variables: if  $f(z)$  is analytic then its real + imaginary parts (viewed as fns of  $x+y$ , where  $z = x+iy$ ) are both harmonic.

(7) variational problems: if  $u_x$  achieves

$$\min_{u=\phi \text{ at } \partial\Omega} \int_{\Omega} W(\nabla u)$$

Then for any  $v$  st  $v|_{\partial\Omega} = 0$  we have

$$t \rightarrow \int_{\Omega} W(\nabla u_x + t \nabla v) \quad \text{has a min at } t=0$$

so, by 1st deriv test,  $\int_{\Omega} \operatorname{div} \left[ \frac{\partial W}{\partial \nabla u}(\nabla u_x) \right] \cdot v \, dx = 0$ .

If  $\text{div} \left[ \frac{\partial W}{\partial \nabla u} (\nabla u) \right]$  were nonzero, there would be a function  $v$  that makes the integral non-zero. So we get the nec condn for optimality:

$$\text{div} \left[ \frac{\partial W}{\partial \nabla u} (\nabla u) \right] = 0$$

Special cases:

a) solving  $\Delta u = 0$  in  $\Omega$ .  $\iff$   $\min_{u=0 \text{ at } \partial\Omega} \int_{\Omega} |\nabla u|^2$

b) solving  $\min_{u=0 \text{ at } \partial\Omega} \int_{\Omega} (1 + |\nabla u|^2)^{1/2}$  (area of graph of  $u$ ).

$$\iff \text{div} \left[ \frac{\nabla u}{(1 + |\nabla u|^2)^{1/2}} \right] = 0$$

This eqn is nonlinear, however if we expect  $\nabla u$  to be small we can take the

small-slope approxn  $(1 + |\nabla u|^2)^{-1/2} \approx 1 - \frac{1}{2} |\nabla u|^2$ .

and we see that the leading-order ("linearized") eqn is  $\Delta u = 0$ .

Let's start with some easy observations abt const-coefft Laplace-type eqns in a bounded domain.

$$(1) \text{ Egn } \Delta u = f \text{ in } \Omega, \\ u = g \text{ at } \partial\Omega$$

can have at most one soln. (In fact, there is a soln; we'll return to this in a couple of weeks).

Pf: subtracting 2 solns, sufft to show  $f=0$  and  $g=0 \Rightarrow u=0$ . Using "energy method": mult eqn by  $u$  to see.

$$\int_{\Omega} u \Delta u = 0 \quad \Rightarrow \quad \int_{\Omega} |\nabla u|^2 = 0.$$

$$\Rightarrow u = \text{const.}$$

Now bdy condn  $\Rightarrow u=0$ .

[Pf can also be done by max prin; we'll discuss max prin later]

$$(2) \text{ Egn } \Delta u = f \text{ in } \Omega$$

$$\frac{\partial u}{\partial n} = g \text{ at } \partial\Omega$$

can have a soln only if  $g + f$  satisfy the consistency condn

$$\int_{\partial\Omega} g \, dA = \int_{\Omega} f \, dx$$

For consistent data, soln is unique up to a constant. (In fact it exists; agr, we'll discuss this later.)

Pf of consistency cond:  $\int_{\Omega} \Delta u = \int_{\partial\Omega} \frac{\partial u}{\partial n}$

for any  $u$ , by Gauss' Thm.

Pf of uniqueness up to const: exactly as before, by "energy method".

What is happening? Recall from linear algebra that if  $A$  is a symmetric  $n \times n$  matrix, then  $Az = b$  has a soln iff  $b \perp \ker A$ .

Also recall that  $\Delta$  is self-adj't for  $L^2$  inner product, with either the bc  $u=0$  at  $\partial\Omega$  or the bc  $\partial u/\partial n = 0$  at  $\partial\Omega$ . We have a consistency condn for the Neumann pbm



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because there's a nontrivial kernel (the constant function) solving  $\Delta u = 0$  when the bc is  $du/dn = 0$ .