

## PDE - Lecture 3, 9/17/2013

We turn now to the heat eqn in  $\mathbb{R}^n$

$$\begin{aligned}u_t - \Delta u &= 0 \quad \text{for } x \in \mathbb{R}^n, t > 0 \\ u &= u_0(x) \quad \text{at } t = 0\end{aligned}$$

(and a little later, related problems for example the heat eqn in a half-space).

What carries over from case of a bdd domain, + what doesn't?

- existence can no longer be done using  $L^2$  eigenfunctions of  $\Delta$ ; instead we'll get an excellent "solution formula" using the "fundamental solution"
- a finite difference repr is possible, but no longer very practical (space is infinite!)
- implicit differencing in time is OK (provided soln decays so  $\int |\nabla u|^2$  is finite)
- uniqueness via energy method is OK. (provided soln decays so  $\int |\nabla u|^2$  is finite)

- uniqueness via max prin requires additional argt, to rule out possibility of  $\bar{u}$  max being achieved as  $|x| \rightarrow \infty$ .

Soln formula, for initial-value pblm on  $\mathbb{R}^n$ : if  $u_0$  is cont's and unit bdd on  $\mathbb{R}^n$  then soln is

$$u(x, t) = \int_{\mathbb{R}^n} \bar{\Phi}(y-x, t) u_0(y) dy$$

with

$$\bar{\Phi}(z, t) = \frac{1}{(4\pi t)^{n/2}} e^{-|z|^2/4t} \quad (\text{"fund soln"})$$

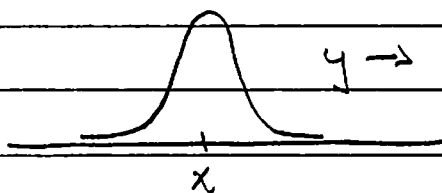
Sketch of p.f:

a)  $\bar{\Phi}_t - \Delta \bar{\Phi} = 0$  (easy to check directly)

b)  $\int_{\mathbb{R}^n} \bar{\Phi}(z, t) dz = 1$  for any  $t$

(easy to check, using that  $\int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}$ )

c) as  $t \rightarrow 0$ ,  $\bar{\Phi}(y-x, t)$  is highly concentrated near  $y=x$



$y \rightarrow \bar{\Phi}(y-x, t)$  is a Gauss cur with variance  $\approx t$

$$d) \int \Phi(x-y, t) u_0(y) dy = \int_{|y-x| < \epsilon} \dots + \int_{|y-x| > \epsilon} \dots$$

As  $t \rightarrow 0$ ,

1<sup>st</sup> term  $\approx u_0(x)$  using cont'g of  $u_0$

2<sup>nd</sup> term  $\approx 0$ , using oddness of  $u_0$ .

Note: Since  $\Phi$  decays exponentially as  $z \rightarrow \infty$  (with  $t$  held fixed), soln formula does not require that  $u_0$  decay at  $\infty$ . In fact it can grow rather rapidly.

How could we have guessed the solution formula?

method 1: we saw in lecture 1 that finite difference approx of heat eqn is assoc to a coin-flipping random walk. So continuum should be assoc to a suitable limit of random walks. Probabilistic interpretn of soln formula:

$\Phi(y-x, t) =$  prob of being at  $y$  at time  $t$ , for a walker who starts at  $x$  at time 0.

Since central limit theorem says distribution of positions after many coin-flips is asymptotically Gaussian, we certainly expect  $\Phi(z,t)$  to be Gaussian w.r.t.  $z$ . (Dependence on  $t$  can be deduced from reqt that  $\int \Phi(z,t) dz = 1$ .)

method 2: Laplacian does have eigenfunctions in  $\mathbb{R}^n$ , namely  $e^{i\xi \cdot x}$  for any  $\xi \in \mathbb{R}^n$ . They're not in  $L^2$ , and they form a continuum rather than a countable family. But the analogue of our basis expansion in  $L^2(\Omega)$  is the Fourier transform:

$$f(x) = (2\pi)^{-n/2} \int e^{ix \cdot \xi} \hat{f}(\xi) d\xi$$

$$\hat{f}(\xi) = (2\pi)^{-n/2} \int e^{-ix \cdot \xi} f(x) dx$$

Since  $\Delta(e^{ix \cdot \xi}) = -|\xi|^2 e^{ix \cdot \xi}$ , soln of initial value prob for heat eqn should be

$$\begin{aligned} u(x,t) &= (2\pi)^{-n/2} \int e^{-|\xi|^2 t} \hat{u}_0(\xi) e^{ix \cdot \xi} d\xi \\ &= (2\pi)^{-n} \int e^{-|\xi|^2 t} e^{i(x \cdot \xi)} e^{-i(y \cdot \xi)} u_0(y) dy d\xi \\ &= \int \Phi(x-y, t) u_0(y) dy \end{aligned}$$

with  $\Phi(z,t) = (2\pi)^{-n} \int e^{-|\xi|^2 t + i(z \cdot \xi)} d\xi$ .

Doing the integral: if  $\eta = \xi\sqrt{t} - \frac{iz}{2\sqrt{t}}$  then

$$\begin{aligned}\Phi(z,t) &= (2\pi)^{-n} \int e^{-|\eta|^2} e^{-|z|^2/4t} t^{-n/2} d\eta \\ &= (2\pi)^{-n} e^{-|z|^2/4t} t^{-n/2} \underbrace{\int e^{-|\eta|^2} d\eta}_{\pi^{n/2}} \\ &= (4\pi t)^{-n/2} e^{-|z|^2/4t}\end{aligned}$$

as expected.

Having  $u(x,t)$  as an "explicit" integral involving  $u_0$  is convenient. Can our "solution formula" for bdd domains be expressed this way? Yes indeed. For example, for

$$\begin{aligned}u_t - \Delta u &= 0 && \text{in } \Omega \text{ (bounded).} \\ u &= 0 && \text{at } \partial\Omega \\ u &= u_0 && \text{at } t=0\end{aligned}$$

$$u(x,t) = \int_{\Omega} G(x,y;t) u_0(y) dy$$

where

$$G(x,y;t) = \sum_{n=1}^{\infty} e^{-\lambda_n t} \varphi_n(x) \varphi_n(y)$$

This is just a rewrite of our soln formula; here  $\phi_n$  are an orthonormal basis of eigenfunctions,  $-\Delta \phi_n = \lambda_n \phi_n$  with  $\phi_n = 0$  at  $\partial\Omega$ ; note that  $G$  is symmetric in  $x+y$ , but no longer a fn of  $x-y$ .

$G(x, y; t)$  is called the "Green's fn" for the heat eqn. (There's an entirely analogous disc'n of course for Neumann bc  $\partial u / \partial \nu = 0$  at  $\partial\Omega$ , using eigenfn's of  $-\Delta$  with  $\partial \phi_n / \partial \nu = 0$ .)

Is soln unique?

- yes, if we assume  $\nabla u \rightarrow 0$  at  $\infty$  fast enough to permit this "energy argt":

$$\frac{d}{dt} \int_{\mathbb{R}^n} \frac{1}{2} |\nabla u|^2 = \int_{\mathbb{R}^n} \langle \nabla u, \nabla u_t \rangle = - \int_{\mathbb{R}^n} \Delta u \cdot u_t$$

If  $u_t = \Delta u$  then RHS becomes  $-\int u_t^2 \leq 0$ . So  $u_t - \Delta u = 0$  and  $u = 0$  initially, & preceding calc justified  $\Rightarrow u = 0$ . (Could also argue using  $\frac{d}{dt} \int_{\mathbb{R}^n} u^2$  as we did in Lecture 1.)

- no, in general: if we permit extreme growth as  $|x| \rightarrow \infty$  there is a nonzero  $\downarrow$  solution of  $u_t - \Delta u = 0$  with initial data 0 (see F. John for an example).

Actually, max principle gives uniqueness with very mild cond on growth as  $|x| \rightarrow \infty$

Max prin for heat eqn in  $\mathbb{R}^n$ : if  $u_t - \Delta u \leq 0$  for  $x \in \mathbb{R}^n$ ,  $0 < t < T$  and also

$$u(x, t) \leq M e^{a|x|^2}$$

for some  $M, a > 0$ , then for  $0 < t < T$  we have

$$u(x, t) \leq \max_{t=0} [u]$$

Pf: May suppose  $T$  is small if necessary (otherwise argue in discrete time steps). We'll specify the smallness condn later,

Consider  $u_\varepsilon(x, t) = u(x, t) - \varepsilon \underbrace{\left( \frac{|x|^2}{4(T-t)} \right)^{-n/2} e^{-|x|^2/4(T-t)}}$

Coefft of  $\varepsilon$  is  $\Phi(x, T-t)$ , so it solves the heat eqn! So  $u_\varepsilon_t - \Delta u_\varepsilon \leq 0$ .

Now look at  $B_\rho \times (0, T)$ ,  $\rho$  sufficiently large.

We know

$$\max_{\substack{|x| \leq \rho \\ 0 \leq t \leq T}} u_\varepsilon \text{ is achieved at } t=0 \\ \text{or else at } |x| = \rho.$$

But at  $|x| = \rho$ ,

$$u_\varepsilon \leq M e^{a\rho^2} - \varepsilon(4\pi T) e^{-a/2 \rho^2/4T}$$

Let's assume  $\frac{1}{4T} > a$ . Then  $\varepsilon$  term wins as  $\rho \rightarrow \infty$ ,  
i.e. rest of  $u_\varepsilon$  to  $|x| = \rho$  approaches  $-\infty$  as  $\rho \rightarrow \infty$ .  
Then using sufficiently large  $\rho$ , we get

$$\max_{\substack{x \in \mathbb{R}^n \\ 0 \leq t \leq T}} u_\varepsilon = \max_{\substack{x \in \mathbb{R}^n \\ t=0}} u_\varepsilon \leq \max_{x \in \mathbb{R}^n} u|_{t=0}$$

Now let  $\varepsilon \rightarrow 0$ .

[Note: there is of course an analogous min principle, using a symmetric arg<sup>t</sup> or applying the max prin to  $-u$ ]

What about heat eqn in a half-space?  
For Dir bc ( $u=0$ ) or Neumann bc ( $\frac{\partial u}{\partial \nu} = 0$ ).  
soln is easy to write down by reflection.



Do it in 1D for simplicity:

$$u_t - u_{xx} = 0 \text{ for } x > 0, \quad u = 0 \text{ at } x = 0$$

$$\Rightarrow u(x, t) = \int_0^{\infty} G(x, y, t) u_0(y) dy$$

where  $G(x, y, t)$  (the Green's fn for a half-space with Dir bc) is

$$(*) \quad G(x, y, t) = \bar{\Phi}(x-y, t) - \bar{\Phi}(x+y, t)$$

Pf: extend  $u_0$  by odd reflection

$$\tilde{u}_0(x) = \begin{cases} u_0(x) & x > 0 \\ -u_0(-x) & x < 0 \end{cases}$$

then apply whole-space soln formula to  $\tilde{u}_0$ .  
Resulting soln is odd in  $x$ , so it vanishes at  $x=0$ .

The case of a Neumann bc is similar:

$$u_t - u_{xx} = 0 \text{ for } x > 0, \quad u_x = 0 \text{ at } x = 0$$

$$\Rightarrow u(x, t) = \int_0^{\infty} N(x, y, t) u_0(y) dy$$

where  $u(x, y, t) = \underline{\underline{\Phi}}(x-y, t) + \underline{\underline{\Phi}}(x+y, t)$ .

Pf: extend  $u_0$  by even reflection

$$\tilde{u}_0(x) = \begin{cases} u_0(x) & x > 0 \\ u_0(-x) & x < 0 \end{cases}$$

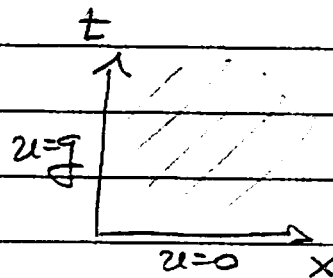
Then apply whole-space soln formula to  $\tilde{u}_0$ .

Resulting soln is even in  $x$ , i.e.  $u(x, t) = u(-x, t)$ .

So  $u_x = 0$  at  $x = 0$ .

What abt halfspace with inhomogeneous boundary data? To fix ideas, let's discuss

$$\begin{aligned} u_t - u_{xx} &= 0 \text{ for } x > 0 \\ u &= g(t) \text{ for } x = 0 \\ u &= 0 \text{ at } t = 0 \end{aligned}$$



Soln is: 
$$u(x, t) = \int_0^t \frac{\partial G}{\partial y}(x, 0, t-s) g(s) ds$$

where  $G$  is the Green's fn of the half-space probn with homog Dir bc (given by eqns (\*) on pg 3.9). After some arithmetic this amounts to

$$u(x, t) = \int_0^t \frac{x}{\sqrt{4\pi(t-s)^{3/2}}} e^{-x^2/4(t-s)} g(s) ds.$$

Proof is simple (and same idea works even in multiple dimensions + for bounded domains).

Fix  $x_0, t_0$  + consider

$$v(y, \tau) = G(x_0, y, t_0 - \tau).$$

It solves heat eqn backward in time, with  $\delta$ -fn singularity at  $y = x_0$  at  $\tau = t_0$ . So

$$\lim_{\tau \uparrow t_0} \int_0^{\infty} v(y, \tau) u(y, \tau) dy = u(x_0, t_0)$$

But

$$\begin{aligned} \frac{d}{ds} \int_0^{\infty} v(y, s) u(y, s) dy &= \int_0^{\infty} v_{\Delta} u + v u_{\Delta} \\ &= \int_0^{\infty} -v_{yy} u + v u_{yy} \end{aligned}$$

$$= -v_y u \Big|_0^{\infty} + v u_y \Big|_0^{\infty}$$

Now,  $v \rightarrow 0$  and  $v_y \rightarrow 0$  as  $y \rightarrow \infty$ , and  $v = 0$  at  $y = 0$ .

So we get

$$\frac{d}{ds} \int_0^{\infty} v(y, s) u(y, s) dy = v_y u \Big|_{y=0}$$

Integrating, and using that  $u = 0$  at  $s = 0$ , we get

$$u(x_0, t_0) = \int_0^{t_0} v_y(0, s) u(0, s) ds$$

which was exactly our assertion.

(Similar argt works with nonzero Neumann data; then of course we must use the Green's fn assoc to a zero Neumann cond, which we called  $N(x, y; t)$  or pg 3.9.)

Nonzero source term? Situation is essentially the same as for bounded domain: soln of

$$\begin{aligned} u_t - \Delta u &= f & \text{for } t > 0 \\ u &= u_0 & \text{at } t = 0 \end{aligned}$$

is

$$u(\cdot, t) = e^{t\Delta} u_0(\cdot) + \int_0^t e^{(t-s)\Delta} f(\cdot, s) ds$$

where now

$$e^{t\Delta} \varphi(\cdot) = \text{soln of heat eqn for time } t \text{ with initial data } \varphi$$

$$= \text{convolution of } \varphi \text{ with the fundamental solution } \Phi(x, t)$$

Bottom line: Some things are easier in  $\mathbb{R}^n$  (or for half-spaces) because we have a very explicit soln formula. Some examples:

- Soln is instantly  $C^\infty$ , no matter how bad  $u_0$  might be (also true for bdd domains, but easier to see in  $\mathbb{R}^n$ ) - just differentiate under the integral in

$$u(x,t) = \int \underline{\Phi}(x-y,t) u_0(y) dy$$

- besides being ill-posed, soln backward in time may cease to exist at a particular time (again, also true for bdd domains but easy to see in  $\mathbb{R}^n$ ) - just consider final-time data  $u(x,T) = \underline{\Phi}(x,T)$ . (Soln backward in  $t$  is  $\underline{\Phi}(x,t)$ , but ceases to exist at  $t=0$ .)