

Calculus of Variations - Lecture 12 - 12/2/09

New topic today: homogenization of uniformly elliptic pde with periodic microstructure.

Motivation:

- (1) another example of Γ -convergence (rather different from Modica-Mortola)
- (2) strong links to physics + materials science, as simplest context where we can discuss "effective models" of materials with microstructure

Some places to read were:

- a) Bensoussan, Lions, Papanicolaou, Asymptotic Analysis for Periodic Structures (a classic)
- b) Cioranescu + Donato, An Introduction to Homogenization (more modern)

(Braides' book on Γ -convergence has a chapter on "Some Homogenization Problems" but the focus is on 1D of one spatial variable; Jost + Li-Jost have a short section on "Homogenization" but the focus is on many well holes with a Dirichlet bc. Interesting + relevant but different from what I do here.)

What is the problem? Want to think abt "effective" or "macroscopic" behavior of a mixture of 2 (or more) materials. Microstructure will be periodic (for simplicity) though similar theory can be developed for random microstrs, or (through a compactness argument) for microstructures with no spatial organization at all

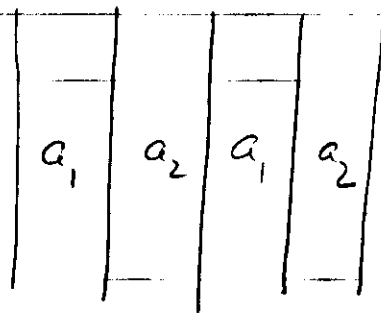
Focus on scalar pde

$$\nabla \cdot (a(\frac{x}{\epsilon}) \nabla u_\epsilon) = f \quad \text{in } \Omega$$

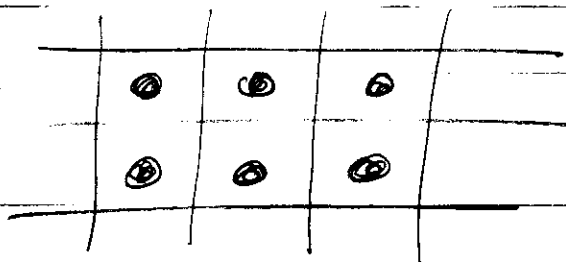
$$u_\epsilon = \varphi \quad \text{at } \partial\Omega$$

where $a(x/\epsilon)$ is real-valued + spatially periodic. To fix ideas, let's focus on case where $a(\cdot)$ takes just two values $a_1 + a_2$ (both positive!).

Examples:



layered microstructure



periodic array of inclusions

Small parameter is $\varepsilon = \frac{\text{length scale of microstr}}{\text{length scale of domain + data}}$.

Link to Γ -convergence: u^ε solves

$$F_\varepsilon(u) = \int_{\Omega} \frac{1}{2} a\left(\frac{x}{\varepsilon}\right) |\nabla u|^2 + u \cdot f \, dx$$

subject to $u = \varphi$ at $\partial\Omega$.

Basic Thm: \exists (constant) matrix a_* , the effective tensor of the composite, st u_ε converges as $\varepsilon \rightarrow 0$ to soln u_* of

$$\begin{aligned} \nabla \cdot (a_* \nabla u_*) &= f & \text{in } \Omega \\ u_* &= \varphi & \text{at } \partial\Omega \end{aligned}$$

Moreover there's a formula for a_* , that depends only on the microstructure (not on f , φ , or Ω):

$$\langle a_* \xi, \xi \rangle = \min_{\varphi \text{ periodic}} \int \langle a(y) (\xi + \nabla \varphi), \xi + \nabla \varphi \rangle$$

where \int denotes the average of a spatially periodic function. Also: $a_* \xi = \int a(y) (\xi + \nabla \varphi^\xi)$ where φ^ξ is optimal for given ξ .

Note that when $a(y)$ is discont's, e.g.

$$\nabla \cdot (a(\frac{x}{\epsilon}) \nabla u_\epsilon) = f$$

means — pde holds in classical sense away from discontinuity

$$(a(\frac{x}{\epsilon}) \nabla u_\epsilon) \cdot \nu \text{ is cont's}$$

$$+ u_\epsilon \text{ is cont's}$$

} across surface where $a(\cdot)$ jumps.

Examples, to build intuition:

① in 1D pde can be solved more or less explicitly

$$(a(x/\epsilon) u_{\epsilon x})_x = f \Rightarrow a(x/\epsilon) u_{\epsilon x} = f + c$$

($c = \text{constant}$)

$$\Rightarrow u_{\epsilon x} = a^{-1}(x/\epsilon) (f + c)$$

Note that $u_{\epsilon x}$ has oscillations of order 1 in magnitude (u_ϵ therefore has osc of order ϵ in magnitude)

Lemma that we'll use repeatedly: if $F(x, y)$ is bounded, cont's, + periodic in y then

$$f_\epsilon(x) = F(x, x/\epsilon)$$

converges weakly in every L^p ($1 < p < \infty$) to

$$f_0(x) = \int F(x,y) dy$$

Pf: easy to see $f_\varepsilon \rightarrow f_0$ as distributions.
Now use boundedness in L^p + standard compactness results.

[Rmk: hypotheses on $F(x,y)$ can be weakened considerably]

Returning to the example: evidently

$$u_\varepsilon \rightarrow u_* \quad (\text{weakly } H^1, \text{ strongly } L^2) \text{ where}$$

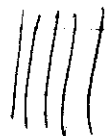
$$u_{*x} = [f a^{-1}(y)] (f(x)+c)$$

$$\Rightarrow \quad \partial_x (a_* \partial_x u_*) = 0, \quad a_* = \left(\int a^{-1} dy \right)^{-1}$$

Nb: if $a(y) = \begin{cases} a_1 & \text{on fraction } \theta_1 \\ a_2 & \text{on fraction } \theta_2 = 1 - \theta_1 \end{cases}$ then

$$a_* = \left(\frac{\theta_1}{a_1} + \frac{\theta_2}{a_2} \right)^{-1} \quad \text{"harmonic mean"}$$

② 2D layered case, with layers $\parallel x_2$ -axis (ie a is a fn of $\frac{x_1}{\varepsilon}$ in (x_1, x_2) plane)



$$\text{Then } a_{\#} = \begin{pmatrix} (f\bar{a}')^{-1} & 0 \\ 0 & fa \end{pmatrix} = \begin{pmatrix} HM & 0 \\ 0 & AM \end{pmatrix}$$

Note the anisotropy! Let's deduce this from the formula for $a_{\#}$ given by the basic theorem:

$$\xi = (1, 0) \Rightarrow \langle a_{\#} \xi, \xi \rangle = \min \{ a(y, 1) \mid |\xi + \eta \varphi|^2 \}$$

is solved by taking $a(y, 1)(1 + \varphi(y)) = \text{constant}$.
 $(\varphi \text{ periodic} \Rightarrow \text{constant must be } (f\bar{a}')^{-1})$
 $\Rightarrow a_{\#}(1, 0) = \int a(y)(\xi + \eta \varphi) = ((f\bar{a}')^{-1}, 0)$

$$\xi = (0, 1) \Rightarrow \langle a_{\#} \xi, \xi \rangle = \min \{ a(y, 1) \mid |\xi + \eta \varphi|^2 \}$$

is solved by taking $\varphi = 0$
 $\Rightarrow a_{\#}(0, 1) = \int a(y)(0, 1) = (0, fa)$

[in both cases we recognized the soln by checking that EL eqn was satisfied; by convexity that's sufficient]

There are 2 ways to explain what's going on:

- asymptotic expansion ("the two-scale method")
- averaging of the var'ial principle.

Both represent useful, generalizable methods, so let's do them both.

Two-scale method: look for expansion

$$u_\varepsilon(x) = u_0(x, \frac{x}{\varepsilon}) + \varepsilon u_1(x, \frac{x}{\varepsilon}) + \varepsilon^2 u_2(x, \frac{x}{\varepsilon}) + \dots$$

where each $u_i(x, y)$ is periodic in its 2nd var "y".

Substitute into eqn: $\frac{\partial}{\partial x_i} \rightarrow \frac{\partial}{\partial x_i} + \varepsilon^{-1} \frac{\partial}{\partial y_i}$

$$\sum_i \left[\frac{\partial}{\partial x_i} + \varepsilon^{-1} \frac{\partial}{\partial y_i} \right] a(y) \left(\frac{\partial}{\partial x_i} + \varepsilon^{-1} \frac{\partial}{\partial y_i} \right) (u_0 + \varepsilon u_1 + \dots) = f$$

Now extract eqns at various orders

order ε^{-2} $\sum_i \frac{\partial}{\partial y_i} \left(a(y) \frac{\partial}{\partial y_i} u_0(x; y) \right) = 0$

view this as pde for $y \rightarrow u_0(x; y)$,
with x as parameter,

Fact: if w is periodic in y + $\nabla \cdot (a(y) \nabla w) = 0$
($w \in H^1$) then $w \equiv \text{constant}$ (ie indep of y).

Pf: multiply eqn by w + integrate by y pts,
to see $\int a(y) |\nabla_y w|^2 = 0$.

So $u_0 = \text{fn of } x \text{ alone: } \boxed{u_0 = u_0(x)}$

Note: Then u_0 is in fact our u_x . But we must proceed to see what pde it solves.

at order ϵ^{-1} :
$$\sum_i \frac{\partial}{\partial y_i} \left[a(y) \frac{\partial u_0}{\partial x_i} \right] + \frac{\partial}{\partial y_i} \left[a(y) \frac{\partial u_1}{\partial y_i} \right] = 0$$

i.e.
$$\operatorname{div}_y (a(y) \nabla_y u_1) = - \operatorname{div}_y (a(y) \nabla_x u_0)$$

This is a pde for $u_1(x, y)$ [with x as a parameter].
Consistency condition is satisfied (RHS has mean 0 w.r. to y).

Examine pde further: we see dependence on $\nabla_x u_0$ is linear. So if \mathcal{F}^i solves

$$\operatorname{div}_y (a(y) \nabla_y \mathcal{F}^i) = - \operatorname{div}_y (a(y) e_i)$$

with $e_i = (0, \dots, \underset{i\text{th place}}{1}, \dots, 0)$, then we can take

$$u_1(x, y) = \sum_i \mathcal{F}^i(y) \frac{\partial u_0}{\partial x_i}$$

(up to an additive fn of x alone).

at order 0: this is where we will get eff eqn of course.

$$\sum_i \frac{\partial}{\partial x_i} \left(a(y) \frac{\partial u_0}{\partial x_i} \right) + \frac{\partial}{\partial y_i} \left(a(y) \frac{\partial u_1}{\partial x_i} \right) + \frac{\partial}{\partial x_i} \left(a(y) \frac{\partial u_1}{\partial y_i} \right) + \frac{\partial}{\partial y_i} \left(a(y) \frac{\partial u_2}{\partial y_i} \right) = f(x).$$

View as pde for u_2 wrt y , with x as parameter, & periodic bc. Consistency cond: data must have avg value 0 wrt y . So

$$\int \frac{\partial}{\partial x_i} \left(a(y) \frac{\partial u_0}{\partial x_i} \right) + \frac{\partial}{\partial x_i} \left(a(y) \frac{\partial u_1}{\partial y_i} \right) dy = 0.$$

Recall that $u_1 = \int \chi(y) \frac{\partial u_0}{\partial x_i}(x) dx$, so

$$a(y) \frac{\partial u_1}{\partial y_i} = \int a(y) \frac{\partial \chi}{\partial y_i} \frac{\partial u_0}{\partial x_i}$$

Thus u_0 solves

$$\nabla \cdot (a_* \nabla_x u_0) = f$$

with

$$(a_*)_{ij} = \int \left[a(y) \delta_{ij} + a(y) \frac{\partial \chi^j}{\partial y_i} \right] dy$$

Rule: From this viewpoint formula for a_* looks rather mysterious. It's not even obvious that $(a_*)_{ij} = (a_*)_{ji}$ - though this is true. Our 2nd, var'l approach will make things clearer.

Variational viewpoint (still formal, but organized around var'l prin rather than pde; better because

it's more intuitive + leads more easily to variational form for a_ε .)

Start with ansatz:

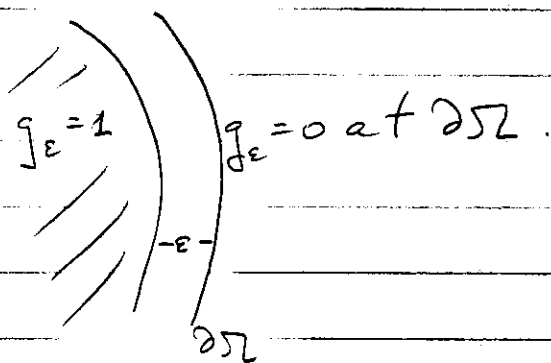
$$u_\varepsilon = u_0(x) + \varepsilon \left(\sum_k \chi^k \left(\frac{x}{\varepsilon} \right) \frac{\partial u_0}{\partial x_k} \right) g_\varepsilon(x)$$

where

u_0 = unknown fn of x (satisfying bc of pde at $\partial\Omega$)

$\chi^k(y)$ = unknown periodic fn of y

$g_\varepsilon(x)$ = fudge to be sure u_ε has proper bc.



(Motivation: 2-scale exp. at order ε^{-1} told us; with a special choice of χ^k ; here we keep the ansatz but leave χ^k to be determined later.)

Substitute into var'l prin \Rightarrow

$$\nabla_x u_\varepsilon = \nabla_x u_0 + \sum_k \nabla_y \chi^k\left(\frac{x}{\varepsilon}\right) \frac{\partial u_0}{\partial x_k} + \text{error terms}$$

(where "error terms" are either of magnitude ε , or else of magnitude 1 supported on an ε -strip near bdy). Ignoring error terms,

$$\int a\left(\frac{x}{\varepsilon}\right) |\nabla u|^2 = \int a(x/\varepsilon) \left| \nabla_x u_0 + \sum_k \nabla_y \chi^k\left(\frac{x}{\varepsilon}\right) \frac{\partial u_0}{\partial x_k} \right|^2$$

RHS has form $F(x, y) \Big|_{y=x/\varepsilon}$, which converges w.r.t. to $\int F(x, y) dy$. So as $\varepsilon \rightarrow 0$, "energy" becomes

$$\int \langle a_* \nabla u_0, \nabla u_0 \rangle$$

where

$$(a_*)_{kl} = \int \sum_i a(y) \left(\delta_{ik} + \frac{\partial \chi^k}{\partial y_i} \right) \left(\delta_{il} + \frac{\partial \chi^l}{\partial y_i} \right) dy$$

Here I used that

$$\left| \nabla_x u_0 + \sum_k \nabla_y \chi^k\left(\frac{x}{\varepsilon}\right) \frac{\partial u_0}{\partial x_k} \right|^2 = \sum_{i,j,k,l} \left(\delta_{ik} + \frac{\partial \chi^k}{\partial y_i} \right) \left(\delta_{il} + \frac{\partial \chi^l}{\partial y_i} \right) \frac{\partial u_0}{\partial x_k} \frac{\partial u_0}{\partial x_l}$$

Explanation of choice of χ^i : for given $\xi = \nabla u_0$, we naturally want to minimize

12.12

$$\begin{aligned} \langle a_x \xi, \xi \rangle &= \int \sum_{i,k,l} a(y) \left(\delta_{ik} + \frac{\partial x^k}{\partial y_i} \right) \left(\delta_{il} + \frac{\partial x^l}{\partial y_i} \right) \xi_k \xi_l \\ &= \int a(y) \left| \xi + \nabla x^\xi \right|^2 \end{aligned}$$

with $x^\xi = \sum \xi^k x^k$. This is our var'ed prin for a_x .
Its Euler eqn is

$$\text{div}_y \left(a(y) \left(\xi + \nabla x^\xi \right) \right) = 0$$

ie

$$\sum_{i,l} \frac{\partial}{\partial y_i} a(y) \left(\delta_{il} + \frac{\partial x^l}{\partial y_i} \right) \xi^l = 0$$

Coefft of ξ^l is precisely the pde we got before, by asymptotic expansion, for x^l .

Suggested exercises

(1) The two scale method led to

$$(a_x)_{ij} = \int a(y) \left(\delta_{ij} + \frac{\partial x^i}{\partial y_j} \right) dy$$

where x^i solves

$$\sum_k \frac{\partial}{\partial y_k} \left(a(y) \left[\delta_{ik} + \frac{\partial x^k}{\partial y_k} \right] \right) = 0$$

Show directly that $(a_*)_{ij} = (a_*)_{ji}$

- (2) The following was assigned already when we did convex duality, but I repeat it as a reminder: from the var'ed principle for a_* , one can show also that

$$\langle (a_*)^{-1} \eta, \eta \rangle = \min_{\substack{dw \tau = 0 \\ \int \tau = \eta}} \int \langle a^{-1}(y) \tau, \tau \rangle dy$$

- (3) Show that

$$(\int a^{-1})^{-1} |\xi|^2 \leq \langle a_* \xi, \xi \rangle \leq (\int a) |\xi|^2.$$

Thus: The eigenvalues of a_* lie between the arithmetic + harmonic means.

- (4) Consider a 2D conducting checkerboard, in which the "red" squares have $a(y) = \alpha$ and the "black" squares have $a(y) = \beta$. Show that $a_* = \sqrt{\alpha\beta}$. (Hint: the "dual" variational principle in problem (2) looks a lot like the original one, if we are in 2D, because we can then take $\tau = \eta + (\nabla\psi)^{\perp}$ with ψ periodic.)