

Calculus of Variations - Lecture 10 - 11/18/09

Looking ahead: plan is

11/18
11/25) Γ -convergence

12/2
12/9) homogenization
12/16

Wed 12/16 is "reading day" but (depending how far we get on 12/9) I may give a lecture that day. If so, it will end in plenty of time for the Holiday Lectures.

New topic today: the "Modica-Mortola problem" (interesting by itself, and as a 1st exposure to Γ -convergence)

Sources:

- Chapter 7 of Jost + Li-Jost is pretty good (it includes lots of technical stuff I'll skip over) but note: it focuses on a slightly different Modica-Mortola example than my focus here.
- Relatively easy reading, + basis of a lot of what I'll do here: RV Kohn + P. Sternberg, "Local minimizers + singular perturbations", Proc

Roy Soc Edinburgh 111A (1989) 69-84

- For Γ -conv. even in presence of a vol constraint, see P. Sternberg's article Arch Rat Mech Anal 101 (1988) 209-260 or L Modica's article Arch Rat Mech Anal 98 (1987) 123-142.
- For Γ -conv. w/o constraint on vol, "Modica-Mortola" problem was discussed by L Modica + S Mortola in Boll. Unione Mat. Italiana - 2 articles in Italian in 1977.

Our goal is to "understand the asymptotic behavior of"

$$F_\varepsilon(u) = \int_{\Omega} \varepsilon |7u|^2 + \frac{1}{\varepsilon} (u^2 - 1)^2 dx$$

in the limit as $\varepsilon \rightarrow 0$ (here $\Omega \subset \mathbb{R}^n$ bdd, + $u: \Omega \rightarrow \mathbb{R}$). Answer will be: F_ε " Γ -converges" to

$$F_0(u) = \begin{cases} \frac{8}{3} \cdot \text{Per}_{\Omega} \{x: u(x) = 1\} & \text{if } u = \pm 1 \text{ a.e.} \\ \infty & \text{otherwise} \end{cases}$$

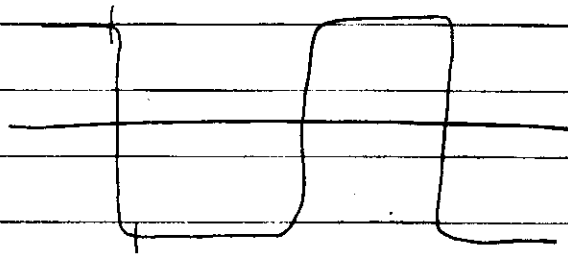
and as consequences

a) if $G(u)$ is compact under L^1 convergence, minimizers of $F_\varepsilon(u) + G(u)$ converge to minimizers of $F_0(u) + G(u)$

b) an isolated L^1 -local min of $F_0(u)$ is the limit as $\varepsilon \rightarrow 0$ of L^1 -local minimizers of F_ε .

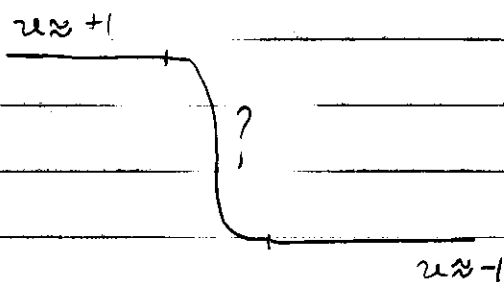
(We'll explain these in due course; but note: the main point of L^1 -convergence is to provide information about minimizers.)

Some intuition first: suppose $\Omega = [0, 1] \subset \mathbb{R}$ and ε is small. If F_ε is not of order $\frac{1}{\varepsilon}$ then $u^2 \approx 1$ so u should be close to ± 1 , except perhaps for some "transitions"



↳ Modica-Mortola asserts: as $\varepsilon \rightarrow 0$, energy required for a transition is exactly $\frac{8}{3}$.

It's easy to see intuitively why this should be true: suppose $u \approx +1$ for $x \leq a$ + $u \approx -1$ for $x \geq b$.



Then

$$\begin{aligned} \int_a^b \epsilon u_x^2 + \frac{1}{\epsilon} (u^2 - 1)^2 &\geq 2 \int_a^b |u^2 - 1| |u_x| \\ &= 2 \int_a^b |\varphi(u)_x| = 2 |\varphi(1) - \varphi(-1)|. \end{aligned}$$

where $\varphi'(t) = |t^2 - 1|$, e.g. $\varphi(t) = \int_{-1}^t |1 - s^2| ds$,
for which

$$-1 < t < 1 \Rightarrow \varphi(t) = t - \frac{1}{3} t^3 \Big|_{-1}^t \Rightarrow \varphi(1) - \varphi(-1) = \frac{4}{3}.$$

Preceding calcn also shows form of the optimal transition: it has

$$\sqrt{\epsilon} |u_x| = \frac{1}{\sqrt{\epsilon}} |u^2 - 1| \quad \text{i.e.} \quad \epsilon u_x = \pm (1 - u^2)$$

This is easily integrated, to show that $u \approx \pm \tanh\left(\frac{x - x_0}{\epsilon}\right)$
in a transition centered at x_0 .

Preceding argument was purely variational - there's

no PDE in sight. But it's related to method of matched asymptotic expansions. Our 1D sol

$$\int_0^1 \epsilon u_x^2 + \frac{1}{\epsilon} (u^2 - 1)^2$$

has only the obvious local minima $u \equiv \pm 1$ (this was an exercise) but it has plenty of saddle pts, which solve

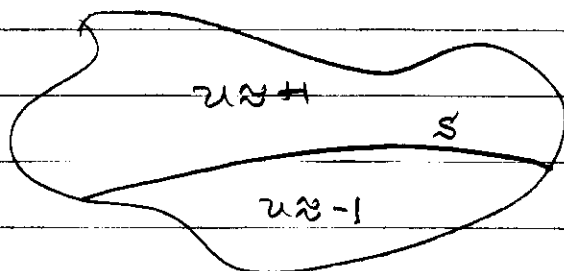
$$-2\epsilon u_{xx} + 4(u^3 - u) = 0 \quad \text{in } (0,1)$$

$$u_x = 0 \quad \text{at endpoints}$$

Low-index saddles can be understood by phase plane analysis - the "transitions" are more or less evenly spaced. One could try to represent the solution of pde by matched asymptotic expansion; the "inner expansion" would lead to the same transition profile we got above. (It's actually difficult to implement this reversibly, because the "outer expansion" involves only terms that are "exponentially small in ϵ ".)

Multidim'l picture is similar - let's focus on 2D - except now "transitions" have more freedom (they're along curves, not at pts). Still,

assertion of Modica - Mortola is that to get



we require the "energy in the transition layer near S " to be at least $\frac{\epsilon}{3} \cdot \text{Length}(S)$,

Infimal α_{ϵ} is as before:

$$\begin{aligned} \int_{\Omega} \epsilon |u|^2 + \frac{1}{\epsilon} (u^2 - 1)^2 &\geq 2 \int_{\Omega} |u| |u^2 - 1| \\ &= 2 \int_{\Omega} |g'(u)| \epsilon |u| \\ &= 2 \int_{\Omega} |g(u)| \end{aligned}$$

If $u_{\epsilon} \rightarrow u_0$ (discont's as in picture) then $g(u_{\epsilon}) \rightarrow g(u_0)$ (discont's across S) and

$$2 \int |g(u_0)| = 2 [g(1) - g(-1)] \cdot \text{Length}(S)$$

since $g(u_0)$ is "a δ -function concentrated at S ".

Moreover, argument shows that u_{ϵ} is (almost) sharp at $u_{\epsilon}(x) = \pm \tanh\left(\frac{d(x, S)}{\epsilon}\right)$, where

$d(x, S) = \text{signed distance to } S,$

More careful statements:

① if $v_\varepsilon \rightarrow v_0$ in L^1 as $\varepsilon \rightarrow 0$, then

$$\liminf F_\varepsilon(v_\varepsilon) \geq F_0(v_0)$$

② if $v_0 \in L^1$ then $\exists v_\varepsilon$ s.t. $v_\varepsilon \rightarrow v_0$ in L^1

+

$$F_\varepsilon(v_\varepsilon) \rightarrow F_0(v_0)$$

These constitute the definition of F_ε Γ -converging to F_0 in the L^1 topology. Also we have

③ if $\{v_\varepsilon\}$ have $F_\varepsilon(v_\varepsilon)$ unit bdd, then $\{v_\varepsilon\}$ is compact in $L^1(\Omega)$

This is why it's natural to study Γ -conv. w.r.t. the L^1 topology.

Our intuitive treatment should have made ① + ② plausible; we'll return to discuss them further (also ③) a bit later. But now let's return to the "consequences".

1st consequence (special case, in 1D): consider

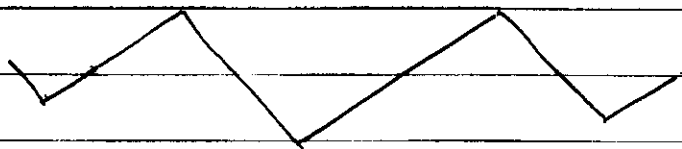
$$E_\varepsilon(u) = \int_0^1 \varepsilon u_{xx}^2 + \frac{1}{\varepsilon} (u_x^2 - 1)^2 + \lambda u^2$$

Modica-Mortola
w.r.t. to u_x

In limit $\varepsilon \rightarrow 0$, it Γ -converges to

$$E_0(u) = \int_0^1 \lambda u^2 dx + \frac{8}{3} \cdot \#(\text{teeth}), \text{ if } u_x = \pm 1$$

(a "sawtooth").



In particular,

$$\min_u E_\varepsilon(u) \text{ converges to } \min E_0(u)$$

and if u_ε minimizes E_ε , its limit pt(s) minimize E_0 .

I've been a bit sloppy: since the anticipated limits are "sawtooth fns" the relevant topology is $u_x \in L^1$, i.e. $W^{1,1}$. The lower order term λu^2 is cpt in this topology, so it does not affect the

Γ -convergence (if $F_\varepsilon \xrightarrow{\Gamma} F_0$ as defined by ①+②
Then $F_\varepsilon + G \xrightarrow{\Gamma} F_0 + G$.)

Claim: Γ -convergence \Rightarrow convergence of minimizers, +
minimizing value.

In fact: if $F_\varepsilon \xrightarrow{\Gamma} F_0$ then

$$\lim (\min F_\varepsilon) \leq \min F_0 \quad \text{by } ②$$

but

$$\lim (\min F_\varepsilon) \geq \min F_0 \quad \text{by } ①$$

So minimizing values converge. Therefore if
 u_ε minimizes F_ε , $F_\varepsilon(u_\varepsilon) \rightarrow \min F_0$. Now
suppose $u_\varepsilon \rightarrow u_0$. Then

$$\liminf F_\varepsilon(v_0) \geq F_0(v_0) \quad \text{by } ①$$

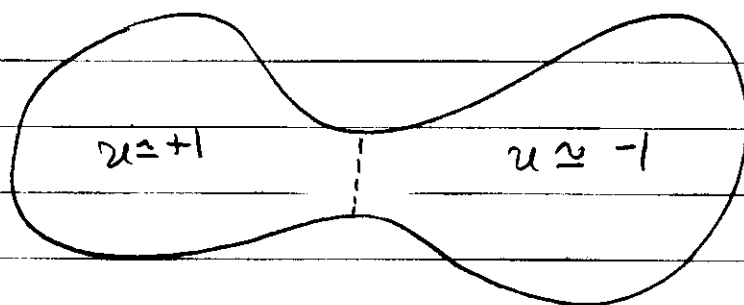
$$\text{So} \quad \min F_0 \geq F_0(v_0)$$

So v_0 must achieve $\min F_0$.

(Note: we used nothing special to Modica-Mortola
here!).

Preceding consequence was "classical." The next is not so classical, but still easy (see the Kohn-Stenberg paper cited on p. 10.1)

Claim: suppose Ω has "a strictly convex neck"



then

① The fn'l. $F_0 = \frac{\varepsilon}{2} \cdot \text{Per}_{\Omega} \{u=1\}$ if $u = \pm 1$

has an isolated L^1 -local min u_0
a transition in the neck.

② $F_{\varepsilon} = \int_{\Omega} \varepsilon |\nabla u|^2 + \frac{1}{\varepsilon} (u^2 - 1)^2$ has a local
min $u_{\varepsilon} \rightarrow u_0$ as $\varepsilon \rightarrow 0$,

Pf of ① is not trivial, but I won't do it (see the paper).

Pf of ② is similar to what we did before:
consider

$$\min_{\|u - u_0\|_{L^1} \leq \delta} F_\varepsilon(u).$$

If u_ε is optimal, then either $\|u_\varepsilon - u_0\|_{L^1} = \delta$ or else the constraint was irrelevant.

Claim: In small ε the constraint is irrelevant.
In fact, by part ② of defn of Γ -conv,

$$\liminf F_\varepsilon(u_\varepsilon) \leq F_0(u_0).$$

If for a seq $\varepsilon_j \rightarrow 0$ we had $\|u_{\varepsilon_j} - u_0\|_{L^1} = \delta$
then in limit $u_{\varepsilon_j} \rightarrow u_*$ we would have

$$\|u_* - u_0\|_{L^1} = \delta$$

but part ② of Γ -conv. says:

$$\liminf F_\varepsilon(u_\varepsilon) \geq F_0(u_*)$$

where $F_0(u_*) \leq F_0(u_0)$. If δ is small but pos, this contradicts hypothesis that u_0 is an L^1 -isolated local min.

OK, so constraint was irrelevant; then u_ε is L^1 local min of F_ε . Easy to see u_ε must $\rightarrow u_0$

as $\epsilon \rightarrow 0$: if not then there would be a seq u_{ϵ_j}

$$\|u_{\epsilon_j} - u_0\|_{L^1} \geq \text{const} > 0$$

so any L^1 limit pt $u_{\epsilon_j} \rightarrow u_*$ has

$$\|u_* - u_0\|_{L^1} \geq \text{const} > 0$$

and (as shown above) $F_0(u_*) \leq F_0(u_0)$.

Again, this contradicts hypoth that u_0 was an isolated local min.

It remains to say a bit more about how properties ①, ②, ③ are proved in the Modica-Mortola example. Next set of notes...